

Product information presented is for internal use within AAT Inc. only. Details are subject to change without notice <u>MULTI-CHANNEL POWER SUPPLY FOR TFT LCD PANELS</u> <u>FULLY I²C INTERFACE CONTROL – TWO BOOST, CHARGE PUMP, BUCK/LDO</u> <u>GPM, PVCOM, TWO OPERATIONAL AMPLIFIER, RESET</u>

FEATURES

- 2.5V to 5.5V Input Supply Voltage Range
- Fully I²C Interface Control
- Current Mode Boost Regulator for V_{AVDD}
 - ◆ 3.6V to 12.7V Output Voltage Range
- Current Mode Boost Regulator for V_{GH}
 - ◆ 10V to 37V Output Voltage Range
 - ◆ Temperature Compensation (T/C)
- Alternative Buck Regulator or Low Dropout Linear Regulator for V₂₅
 - ◆ 1.5V to 3.0V Output Voltage Range
- Negative Charge Pump Linear Regulator for V_{GL}
 - ◆ -4.5V to -8.0V Output Voltage Range
- Unit-Gain Buffer for V_{COM}
 - ◆ 7 Bits, 128-Step Adjustable Sink Current Output
 - ◆ ±200mA Short-Circuit Current
 - ♦ 12V/µs Slew Rate
 - ◆ Temperature Compensation (T/C)
- Two Operational Amplifier
 - ±120mA Short-Circuit Current
 - ♦ 12V/µs Slew Rate
- Gate Pulse Modulation (GPM)
- RESET Output (XAO)
 - Open Drain Output
- Protection
 - Over Voltage Protection (OVP)
 - Under Voltage Protection (UVP)
 - Short Circuit Protection (SCP)
 - Over Temperature Protection (OTP)
- WQFN 28-3.5mmX5.5mmX0.75mm Package

GENERAL DESCRIPTION

The AAT1277 is a highly integrated power management IC for TFT LCD panels. The device consists of two current mode boost regulators, a current mode buck regulator or a low dropout linear regulator alternatively, a negative charge pump linear regulator, a gate pulse modulation, a reset function, a unit-gain VCOM buffer and two operational amplifiers. The AAT1277 also includes I²C interface for setting various parameters such as each regulator's output voltage, switching frequency, soft start time, delay times, etc.

The AAT1277 includes a current mode synchronous boost regulator that provides a fast transient response supply voltage for the source driver. The source driver boost is capable of generating up to 12.7V. A second current mode non-synchronous boost supplies the gate-on voltage, and is capable of an output voltage of up to 37V. The VGH boost includes a temperature compensation function. For improving TFT LCD image quality, a gate pulse modulation (GPM) circuit shapes the gate-on signal. The slope of the gate-on voltage can be set by external resistor.

The logic power voltage (V25) could be supplied either by the buck regulator or by LDO alternatively and programmed via I²C from 1.5V to 3V. The synchronous current mode buck regulator operates at a fixed switching frequency of 1.2MHz, and provides fast load transient response to pulsed loads while producing efficiencies over 90%. The low dropout linear regulator (LDO) output voltage guarantees a minimum 350mA output current limit.

The AAT1277 negative charge pump linear regulator generates VGL supply voltage for the gate-off voltage.

The programmable operational amplifier drives the LCD backplane (VCOM). This unity-gain buffer is capable of

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Version 0.03

Page 1 of 44



Advanced Analog Technology, Inc.

AAT1277

rail-to-rail input and output, ± 200 mA output short-circuit current, and a 12V/µs slew rate. Output voltage can be programmed by I²C interface using 7-bits or 128 steps, eliminating mechanical potentiometers to reduce labor cost.

Two operational amplifiers are included for the Panel repair-line. Those are not controlled by I^2C interface and their outputs are set using an external signal.

The reset functions (RESET) is used to monitor the V25 voltage. The reset signal is issued via an open drain NMOS when the supply is below a programmable thresholds voltage.

The AAT1277 device includes various protection features such as input under-voltage lockout (UVLO) and

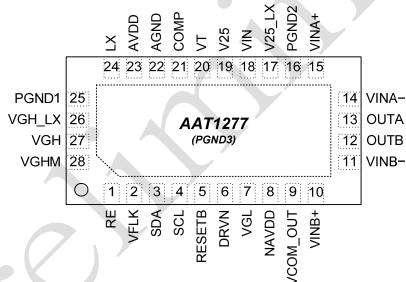
over temperature shutdown (OTP). Regulator outputs include under voltage protection (UVP), overload voltage protection (OVP), and short circuit protection (SCP).

The AAT1277 is available in a small WQFN 28 pin 3.5mmX5.5mmX0.75mm with a bottom side exposed thermal pad to provide optimal heat dissipation. The device is rated to operate from -40 to +85°C temperature range.

APPLICATIONS

- Tablet Panel
- Notebook Panel





ORDERING INFORMATION

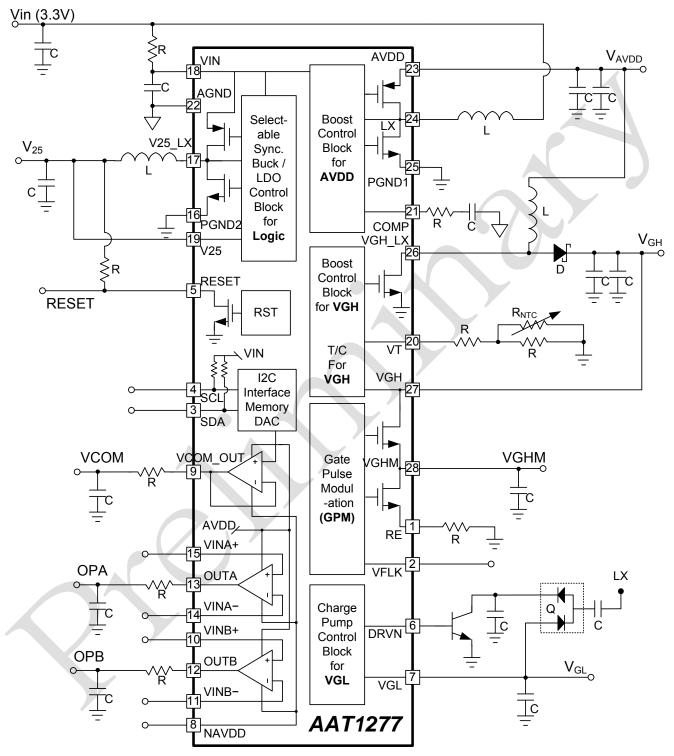
DEVICE TYPE	PART NUMBER	PACKAGE	PACKING	TEMP. RANGE	MARKING	MARKING DESCRIPTION
AAT1277	AAT1277 -Q45-T	Q45: WQFN28- 3.5X5.5	T: Tape and Reel	–40 °C to +85 °C	1277 XXXXXX XXXX	Device Type Lot no. (6~9 Digits) Date Code (4 Digits)

Note: All AAT products are lead free and halogen free.

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Version 0.03
Page 2 of 44



TYPICAL APPLICATION



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Version 0.03
Page 3 of 44



ABSOLUTE MAXIMUM RATINGS

PARAMETER	SYMBOL	VALUE	UNIT
VIN to AGND	V _{IN}	-0.3 to +6.5	V
PGND1, PGND2 to AGND	-	-0.3 to +0.3	V
LX to PGND1	V _{H1}	-0.3 to +16.0	V
V25_LX to PGND2	V _{H2}	-0.3 to +6.5	V
VGH_LX to PGND1	V _{H3}	-0.3 to +45.0	V
DRVN to PGND1	V _{H4}	-12.0 to +0.3	V
Input Voltage 1 (SCL, SDA, V25, VFLK)	V _{I1}	–0.3 to V _{IN} +0.3	V
Input Voltage 2 (AVDD)	V _{I2}	–0.3 to V _{H1} +0.3	V
Input Voltage 3 (NAVDD)	V _{I3}	V _{H4} –0.3 to +0.3	V
Input Voltage 3 (VGH)	V _{I4}	–0.3 to V _{H3} +0.3	V
Input Voltage 4 (VGL)	V _{I4}	V _{H4} -0.3 to +0.3	V
Output Voltage 1 (COMP, VT, RESETB)	V ₀₁	–0.3 to V _{IN} +0.3	V
Output Voltage 2 (VCOM_OUT, OUTA, OUTB, VINA+, VINB+, VINA–, VINB–)	V _{O2}	V_{H4} –0.3 to V_{H1} +0.3	V
Output Voltage 3 (VGHM, RE)	V _{O3}	–0.3 to V_{H3} +0.3	V
Operating Ambient Temperature Range	T _A	-40 to +85	°C
Operating Junction Temperature Range	TJ	-40 to +150	°C
Storage Temperature Range	T _{STORAGE}	–65 to +150	°C
Package Thermal Resistance	θ _{JA}	31.88	°C/W
Power Dissipation, @ T_A = +25 ° C , T_J = +125 ° C	P _d	3.137	W
ESD Susceptibility Human Body Mode	НВМ	2k	V
ESD Susceptibility Machine Mode	MM	200	V

Note:

1. Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device.

2. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.



ELECTRICAL CHARACTERISTICS

 $(V_{IN} = 2.5V \text{ to } 5.5V, T_A = -40 \degree \text{C} \text{ to } +85 \degree \text{C}$, unless otherwise specified. Typical values are tested at +25 °C ambient temperature, $V_{IN} = 3.3V$, $V_{AVDD} = 8.5V$, $V_{GH} = 23V$, $V_{GL} = -6V$, $V_{25} = 2.5V$, NAVDD = GND)

Operating Power

PARAMETER	SYMBOL	TEST CONDITION	MIN	TYP	МАХ	UNIT
VIN Input Voltage Range	V _{IN}		2.5	-	5.5	V
		Rising	2.30	2.35	2.40	V
Under Voltage Lockout Threshold	V _{UVLO}	Falling	2.1	2.2	2.3	V
-		Hysteresis	100	150	200	mV
	I _{IN}	Not Switching	(- /		2	mA
Quiescent Current		Switching	-(6	-	mA
Thermal Shutdown	T _{SH}		-	150	-	°C
Supply Current Into AVDD			_	5.0	8.5	mA
Supply Current Into VGH			-	0.1	1.0	mA
VIN Stress		Pulse Width 100ms	-	-	12	V



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Synchronous Current Mode Boost Regulator (V_{AVDD})

PARAMETER	SYMBOL	TEST CONDITION	MIN	TYP	МАХ	UNIT
AVDD Output Voltage Accuracy			-1	-	+1	%
AVDD Output Voltage Range	V _{AVDD}	7Bits, Step = 0.1V	3.60	0	12.7	V
LX Opsillation Fragmanny	£	2 Bits, Step = 200kHz	600	<u> </u>	1200	kHz
LX Oscillation Frequency	f _{OSC_AVDD}	Tolerance	-20	-	+20	%
IX Current Limit		1 Bits, Step = 1A Tolerance ±20%	0.8	1.0	1.2	А
LX Current Limit	I _{LIM_LX}		1.6	2.0	2.4	А
LX NMOS ON-Resistance	R _{ON1_NMOS}		-	0.2	0.3	Ω
LX NMOS Leakage Current	I _{Leak1_NMOS})-	10	20	μA
LX PMOS ON-Resistance	R _{ON1_PMOS}		-	0.8	-	Ω
LX PMOS Leakage Current	I _{Leak1_PMOS}		-	1	20	μA
LX Maximum Duty Cycle	D _{MAX_LX}	V_{IN} = 2.5, V_{AVDD} = 11V, H = 0.8, f_{OSC_LX} = 1.2MHz	79.8	81.8	-	%
Line Regulation	V _{LINE_AVDD}	V _{IN} = 2.5V to 5.5V, I _{AVDD} = 200mA	-	±0.1	±0.15	%/V
Load Regulation	VLOAD_AVDD	V _{IN} = 3.3V, I _{AVDD} = 20 to 200mA	-1	-	+1	%
Coff Start Time		2 Bits, Step = 20ms	20	-	80	Ms
Soft Start Time	t _{ss_avdd}	Tolerance	-10	0.2 0.3 10 20 0.8 - 1 20 81.8 - ± 0.1 ± 0.15 ± 0.1 ± 0.15 $ +10$ $ +10$ $ 1.1$ 15.0 15.5	+10	%
LX Switch ON / OFF Slew Rate	TS _{LX}	2 Bits, Step = 0.2 V/ns	0.5	-	1.1	V/ns
Over Meltage Drotect Meltage	N		14.5	15.0	15.5	V
Over Voltage Protect Voltage	V _{OVP_AVDD}	Hysteresis	1.129	1.250	1.375	V
(Inder)/oltage Drotect)/oltage			75	80	85	%
Under Voltage Protect Voltage	V _{UVP_AVDD}	V _{AVDD} Rising – V _{AVDD} Falling	0.5	1.5	2.5	%
Duration to UVP Trigger Time	t _{UVP_AVDD}		140	160	180	Ms
Short Circuit Protect Voltage	V _{SCP_AVDD}		25	30	35	%



ELECTRICAL CHARACTERISTICS

 $(V_{\text{IN}} = 2.5\text{V to } 5.5\text{V}, \text{ } T_{\text{A}} = -40\,^{\circ}\text{C to } +85\,^{\circ}\text{C}, \text{ unless otherwise specified. Typical values are tested at } +25\,^{\circ}\text{C} \text{ ambient temperature, } V_{\text{IN}} = 3.3\text{V}, \text{ } V_{\text{AVDD}} = 8.5\text{V}, \text{ } V_{\text{GH}} = 23\text{V}, \text{ } V_{\text{GL}} = -6\text{V}, \text{ } V_{25} = 2.5\text{V}, \text{ } \text{NAVDD} = \text{GND})$

Current Mode Boost Regulator (V_{GH})

PARAMETER	SYMBOL	TEST CONDITION	MIN	TYP	MAX	UNIT
VGH Output Voltage Accuracy	N		-1	-	+1	%
VGH Output Voltage Range	V _{GH}	5 Bits, Step = 1V	10	-	37	V
	£		320	400	480	kHz
VGH_LX Oscillation Frequency	f _{osc_vgн}	1 Bits, Step = 400kHz	640	800	960	kHz
VGH_LX Current Limit	I _{LIM_ VGH}		1.2	1.5	1.8	А
VGH_LX NMOS ON-Resistance	R _{ON2_NMOS}		-	1.3	2.0	Ω
VGH_LX NMOS Leakage Current	I _{Leak2_NMOS}		-	10	20	μA
VGH_LX Maximum Duty Cycle	D _{MAX_VGH}	V_{AVDD} = 3.6, V_{GH} = 30V, η = 0.8, f_{OSC2} = 800kHz	88.4	90.4	-	%
Line Regulation	$V_{\text{LINE}_{\text{VGH}}}$	V_{AVDD} = 3.6 to 12.7V, I_{VGH} = 20mA	-	0.1	0.15	%/V
Load Regulation	$V_{\text{LOAD}_{\text{VGH}}}$	I _{GH} = 5 to 40mA	-1	-	+1	%
Soft Start Time	t _{ss_vghl} -	2 Bits, Step = 2ms	4	-	10	Ms
		Tolerance	-10	-	+10	%
LX Switch ON / OFF Slew Rate	TS_{VGH}	2 Bits, Step = 1.3 V/ns	2.2	-	6.0	V/ns
Over Voltage Protect Voltage	V		38	39	40	V
Over vollage Flotect vollage	V _{OVP_VGH}	Hysteresis	0.45	0.50	0.55	V
Under Voltage Protect Voltage	V		75	80	85	%
Under vollage Protect vollage	V _{UVP_VGH}	V_{VGH} Rising – V_{VGH} Falling	0.5	1.0	1.5	%
Duration to UVP Trigger Time	t _{UVP_VGH}		140	160	180	Ms
Short Circuit Protect Voltage	$V_{\text{SCP}_{VGH}}$		25	30	35	%
VGHT Output Voltage Accuracy	N/		-1	-	+1	%
VGHT Output Voltage Range	– V _{GHT}	5 Bits, Step = 1V	10	-	37	V
VT Source Current	I _{VT}	V _{VT} = 1V	39	40	41	μA
VT Low Temperature Voltage	VT_LT		-	0.5	-	V
VT Low Temperature Voltage	VT_HT		-	1.25	-	V

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Version 0.03

Page 7 of 44



ELECTRICAL CHARACTERISTICS

 $(V_{IN} = 2.5V \text{ to } 5.5V, T_A = -40 \degree \text{C} \text{ to } +85 \degree \text{C}$, unless otherwise specified. Typical values are tested at +25 °C ambient temperature, $V_{IN} = 3.3V$, $V_{AVDD} = 8.5V$, $V_{GH} = 23V$, $V_{GL} = -6V$, $V_{25} = 2.5V$, NAVDD = GND)

Current Mode Buck Regulator (V25_BUCK)

PARAMETER	SYMBOL	TEST CONDITION	MIN	TYP	МАХ	UNIT
V25 Output Voltage Accuracy			-1	-	+1	%
V/25 Output Voltage Bange	V ₂₅	4 Bits, Step = 0.1V	1.5	-	3.0	V
V25 Output Voltage Range		5 Bits, Step = 0.1V	1.0	A-	3.0	V
V25_LX Oscillation Frequency	f _{OSC_V25}		0.96	1.20	1.44	MHz
V25_LX Current Limit	I _{LIM_ V25_LX}		1.0	1.2	1.4	А
V25_LX NMOS ON-Resistance	R _{ON3_NMOS}			80	100	mΩ
V25 PMOS On-Resistance	R _{ON3_PMOS}		-	250	350	mΩ
V25_LX NMOS Leakage Current	I _{Leak3_MOS}		-	10	20	μA
Line Regulation	V_{LINE_V25}	V _{IN} = 2.8 to 5.5V, I _{V25} = 200mA	-	±0.25	±0.5	%/V
Load Regulation	$V_{LOAD_{V25}}$	V_{IN} = 3.3V, I_{GH} = 1 to 400mA	—1	-	+1	%
Soft Start Time	t _{SS3}		3.2	4.0	4.8	Ms
Linder Voltage Dratest Voltage	V		0.7	0.8	0.9	V
Under Voltage Protect Voltage	V_{UVP_V25}	V_{25} Rising – V_{25} Falling	100	150	200	mV
Duration to UVP Trigger Time	t _{UVP_V25}		140	160	180	Ms
Short Circuit Protect Voltage	V _{SCP_V25}		0.25	0.30	0.35	V

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Advanced Analog Technology, Inc. –
Version 0.03
Page 8 of 44



ELECTRICAL CHARACTERISTICS

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Low Dropout Linear Regulator (V25_LDO)

PARAMETER	SYMBOL	TEST CONDITION	MIN	TYP	МАХ	UNIT
Input Voltage Range	V _{LDOI}		2.5	-	5.5	V
Output Voltage Accuracy			-1%	0	+1%	V
Output Valtage Denge	V ₂₅	4 Bits, Step = 0.1V	1.5	A-	3.0	V
Output Voltage Range		5 Bits, Step = 0.1V	1.0	-	3.0	V
Dropout Voltage	V _{DROP}	V _{IN} = 3.3V, I _{LDO} = 350mA	(- /	300	500	mV
LDO Output Current Limit	I _{lim_ldo}		350	500	650	mA
Quiescent Current	I _{Q_LDO}		-	60	100	μA
Line Regulation	V _{LINE_LDO}	V_{IN} = 2.8 to 5.5V, V_{LDOO} = 2.5V, I_{LDO} = 150mA	-	0.1	0.3	%/V
Load Regulation	V _{LOAD_LDO}	V_{IN} = 3.3V, V_{LDOO} = 2.5V, I_{LDO} = 1 to 300mA	-	0.2	0.5	%
Linder Voltage Protect Voltage	V		0.7	0.8	0.9	V
Under Voltage Protect Voltage	V _{UVP_LDO}	V_{LDOO} Rising – V_{LDOO} Falling	100	150	200	mV
Duration to UVP Trigger Time	t _{UVP_LDO}		140	160	180	ms
Short Circuit Protect Voltage	V _{SCP_V25}		0.25	0.30	0.35	V

- 台灣類比科技股份有限公司 -- Advanced Analog Technology, Inc. -Version 0.03 Page 9 of 44



ELECTRICAL CHARACTERISTICS

 $(V_{\text{IN}} = 2.5\text{V to } 5.5\text{V}, \text{ } T_{\text{A}} = -40\,^{\circ}\text{C to } +85\,^{\circ}\text{C}, \text{ unless otherwise specified. Typical values are tested at } +25\,^{\circ}\text{C} \text{ ambient temperature, } V_{\text{IN}} = 3.3\text{V}, \text{ } V_{\text{AVDD}} = 8.5\text{V}, \text{ } V_{\text{GH}} = 23\text{V}, \text{ } V_{\text{GL}} = -6\text{V}, \text{ } V_{25} = 2.5\text{V}, \text{ } \text{NAVDD} = \text{GND})$

Negative Charge Pump Regulator (for VGL)

PARAMETER	SYMBOL	TEST CONDITION	MIN	TYP	МАХ	UNIT
VGL Output Voltage Accuracy			-1	-	+1	%
Output Voltage Range	V _{GL}	6 Bits, Step = –0.1V	-8.0	-	-4.5	V
DRVN Source Current	I _{DRVN}		1	4	6	mA
Soft Start Time		2 Bits, Step = 2ms	4	-	10	ms
Solt Start Time	t _{ss_vghL}	Tolerance	-10		+10	%
Under Voltage Protect Voltage	V_{UVP_VGL}		75	80	85	%
Duration to UVP Trigger Time	t _{UVP_BUCK}		140	160	180	ms
Short Circuit Protect Voltage	V_{SCP_VGL}		25	30	35	%
Line Regulation	V _{LINE_VGL}	V _{IN} = 2.5 to 5.5V, I _{DRVN} = 0.1mA	-	1	6	mV
Effective Load Regulation Error	V _{LOAD_VGL}	$V_{GL} = -8V$, $I_{DRVN} = 50\mu A$ to 1mA	-30	-5	-	mV

Gate Pulse Modulation (GPM)

PARAMETER	SYMBOL	TEST CONDITION	MIN	TYP	MAX	UNIT
VFLK Input Low Voltage	V_{IL_VFLK}		-	-	0.6	V
VFLK Input High Voltage	V _{IH_VFLK}		1.5	-	-	V
VFLK Input Bias Current	Ів4	V _{FLK} = 0 to VIN_LCD	-40	-	+40	nA
Propagation Delay VFLK to VGHM	tpp	V _{GH} = 20V	-	100	120	ns
VGH to VGHM Switch ON Resistance	Ron_sc		10	30	50	Ω
RE to VGHM Switch ON Resistance	Ron_dc		10	25	50	Ω
Delay Time (GPM)	t _{DLY}	2Bits, Step = 20ms	-	-	60	ms
Delay Time Tolerance (GPM)			-10	-	+10	%



ELECTRICAL CHARACTERISTICS

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RESETB SYMBOL UNIT PARAMETER **TEST CONDITION** MIN TYP MAX $I_{RST} = 1.2mA$ V_{RST} V **RESETB** Output Voltage 0.2 --Leakage Current $V_{RST} = 2.5V$ -1 μΑ -V 3Bits, Step = 0.2V 1.2 2.6 -**RESETB Detect Voltage** VDIV Tolerance -8 -+8 % Hysteresis V_{HYS_DVI} 100 150 200 mV 4 Bits, Step = 2ms 30 -0 ms **RESETB Delay Time** t_{RST} Tolerance -10 10 % _

Programmable VCOM Buffer (VCOM)

PARAMETER	SYMBOL	TEST CONDITION	MIN	TYP	MAX	UNIT
AVDD Input Voltage Range	V _{OPPI}	AVDD-NAVDD < 18V	3.6	-	12.7	V
NAVDD Input Voltage Range	V _{OPNI}	AVDD-NAVDD < 18V	-8	-	-	V
VCOM Output Voltage Range		8Bits, Step = 0.1V	-4.1	-	+5.1	V
VCOM Output Voltage Accuracy	V _{COM}		-6		+6	LSB
VCOMT Output Voltage Range	N	8Bits, Step = 0.1V	-4.1	-	+5.1	V
VCOMT Output Voltage Accuracy	. V _{сомт}	7	-6	-	+6	LSB
Load Regulation		I _{OUT} = 1 to 20mA Sourcing	-	1	2	V/A
		I _{OUT} = 1 to 20mA Sinking	-	1	2	V/A
Short Circuit Current (FAVDD Type)	I _{SHORT}	Measure I _{OP_OUT}	-	±200	-	mA
Short Circuit Current (±AVDD Type)	I _{SHORT}	Measure I _{OP_OUT}	-	±200	-	mA
Slew Rate	SR		8	12	-	V/µs
Settling Time	t _s	$\pm 0.1\%$, V _{OUT} = 2V step, A _V = 1, AVDD = 5V, NAVDD = -5V	-	500	-	ns
Power Supply Rejection Ratio	PSRR	Product	-	85	-	dB
Bandwidth	BW	–3dB	12	-	-	MHz
Gain- Bandwidth		Buffer Configuration	8	-	-	MHz

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Version 0.03

Page 11 of 44



ELECTRICAL CHARACTERISTICS

 $(V_{\text{IN}} = 2.5V \text{ to } 5.5V, T_{\text{A}} = -40 \,^{\circ}\text{C} \text{ to } +85 \,^{\circ}\text{C}, \text{ unless otherwise specified. Typical values are tested at } +25 \,^{\circ}\text{C} \text{ ambient temperature, } V_{\text{IN}} = 3.3V, V_{\text{AVDD}} = 8.5V, V_{\text{GH}} = 23V, V_{\text{GL}} = -6V, V_{25} = 2.5V, \text{NAVDD} = \text{GND})$

Operational Amplifier (2 OP)

PARAMETER	SYMBOL	TEST CONDITION	MIN	TYP	МАХ	UNIT
AVDD Input Voltage Range	V _{OP}	AVDD-NAVDD < 18V	3.6 0	-	12.7	V
NAVDD Input Voltage Range	V _{OP}	AVDD-NAVDD < 18V	-8	0	0	V
Input Supply Current	I _{OP}		-	3	-	mA
Input Offset Voltage	V _{OPIN}	V _{CM} = 0V		2	15	mV
Average Offset Voltage Drift		$T_A = -40 \circ C$ to $+85 \circ C$	(- /	5	-	µV/°C
Input Bias Current	I _{B_OPIN}	V _{CM} = 0V	-40	<u> </u>	+40	nA
Input Impedance	RI _N		-	1	-	GΩ
Input Capacitance	C _{IN}		-	1.35	-	pF
Input Common mode Voltage Range	V _{CM}		-5.5	-	+5.5	V
Common mode Rejection Ratio	CMRR	$V_{OPIN} = -5.5V$ to +5.5V	50	80	-	dB
Power Supply Rejection Ratio	PSRR		60	70	-	dB
Open Loop Gain	A _{VOL}	V _{OP_OUT} = -4.5V to +4.5V	75	95	-	dB
Output Swing	V _{OP_SL}	$I_{OP_OUT} = -5mA,$ $V_{OP_IN} = -5V$	-	-4.92	-4.85	V
5	V _{OP_SH}	I_{OP_OUT} =+5mA, V_{OP_IN} = 5V	4.85	4.92	-	V
Continuous Output Current	I _{CONT}		-	±35	-	mA
Short Circuit Current	I _{SHORT}	Measure I _{OP_OUT}	-	±120	-	mA
Slew Rate	SR	V _{OP_OUT} = -4V to +4V, 20% to 80%	8	12	-	V/µs
Settling Time	t _s	±0.1%, V _{OUT} = 2V step, AV = 1, AVDD = 5V, NAVDD = -5V	-	500	-	ns
Bandwidth	BW	–3dB, RL = 10kΩ, CL = 10pF	-	12	-	MHz
Gain- Bandwidth Product	GBPW	RL = 10kΩ, CL = 10pF	-	5	-	MHz
Phase Margin	PM	RL = 10kΩ, CL = 10pF	-	50	-	0
Channel Seperation	CS	f = 5MHz	-	75	-	dB



ELECTRICAL CHARACTERISTICS

 $(V_{\text{IN}} = 2.5V \text{ to } 5.5V, T_{\text{A}} = -40 \,^{\circ}\text{C} \text{ to } +85 \,^{\circ}\text{C}, \text{ unless otherwise specified. Typical values are tested at } +25 \,^{\circ}\text{C} \text{ ambient temperature, } V_{\text{IN}} = 3.3V, V_{\text{AVDD}} = 8.5V, V_{\text{GH}} = 23V, V_{\text{GL}} = -6V, V_{25} = 2.5V, \text{NAVDD} = \text{GND})$

I²C Interface

PARAMETER	SYMBOL	TEST CONDITION	MIN	TYP	МАХ	UNIT
SCL, SDA Input High Voltage	V _{IH2}		1.5	-	-	V
SCL, SDA Input Low Voltage	V _{IL2}		-		0.6	V
SCL, SDA Input Capacitance	C _{SI}		-	5р	-	F
SDA Output Low Voltage	V _{OL}	I _{SINK} = 3mA	-	-	0.4	V
SCL Clock Frequency	f _{OSCI2C}		(- 7)	400k	Hz
SCL Clock High Period	t _{IH3}		0.6		-	μs
SCL Clock Low Period	t _{IL3}		1.3	-	-	μs
SCL, SDA Receiving Rise Time	t _{R1}) -	20+0.1* C _B	300	ns
SCL, SDA Receiving Fall Time	t _{F1}		-	20+0.1* С _в	300	ns
I ² C Data Setup Time	t _{S1}		100	-	-	ns
I ² C Data Hold Time	t _{H1}		-	-	900	ns
I ² C Setup Time for START Condition	t _{S2}		0.6	-	-	μs
I ² C Hold Time for START Condition	t _{H2}		0.6	-	-	μs
I ² C Bus Free Time Between STOP and START Conditions	t _{BUS}		4.7	-	-	μs
I ² C Pulse Width of Suppressed Spike	t _{PS}		-	-	50	ns
I ² C Bus Capacitance	C _B		-	-	400	pF
SDA, SCL Pull Up Resistor	R _{PU}		4.7	10.0	-	kΩ

NVM

PARAMETER	SYMBOL	TEST CONDITION	MIN	TYP	MAX	UNIT
Byte Write Time	t _{BYTE}		-	-	10	ms
Byte Read Access Time	B _{RT}		-	200	-	ns
NVM Programmable Times	N _{NVM}		-	1,000		Cycle



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November 2015

AAT1277

PIN DE	SCRIP	FION
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PIN NO.	NAME	I/O	DESCRIPTION
1	RE	0	GPM Falling Time Setting Pin
2	VFLK	1	GPM Control Pin (High: VGHM=VGH, Low: VGHM=Discharge)
3	SDA	I	I ² C Compatible Serial Data Input/Output
4	SCL	I	I ² C Compatible Serial Clock Input
5	RESETB	0	Voltage Detector Output for Resetb
6	DRVN	0	Voltage Driver Output of Negative Charge Pump Linear Regulator
7	VGL	I	Output Sensing of Negative Charge Pump Linear Regulator
8	NAVDD	I	Negative Input of VCOM and Operational Amplifiers
9	VCOM_OUT	0	VCOM Buffer Output
10	VINB+	I	Non-Inverting Input of Operational Amplifier B
11	VINB-	I	Inverting Input of Operational Amplifier B
12	OUTB	0	Operational Amplifier B Output
13	OUTA	0	Operational Amplifier A Output
14	VINA-	I	Inverting Input of Operational Amplifier A
15	VINA+	I	Non-Inverting Input of Operational Amplifier A
16	PGND2	-	Power Ground for Buck Regulator
17	V25_LX	0	Switch Node of Buck Regulator or LDO
18	VIN	I	Power Supply Input
19	V25	I	Output Sensing of Buck Regulator or LDO
20	VT	0	Negative Temperature Compensation Pin for VGH and VCOM
21	COMP	0	Compensation Pin for AVDD Boost Regulator
22	AGND	-	Analog Ground
23	AVDD		Output Sensing of AVDD Boost Regulator, Positive Input of VCOM and Operational Amplifiers
24	LX	0	Switch Node of AVDD Boost Regulator
25	PGND1	-	Power Ground for VGH Regulator
26	VGH_LX	0	Switch Node of VGH_LX Boost Regulator
27	VGH	I	Output Sensing of VGH Boost Regulator
28	VGHM	0	Gate Pulse Modulation (GPM) Output
29	PGND3	-	Power Ground for AVDD Regulator

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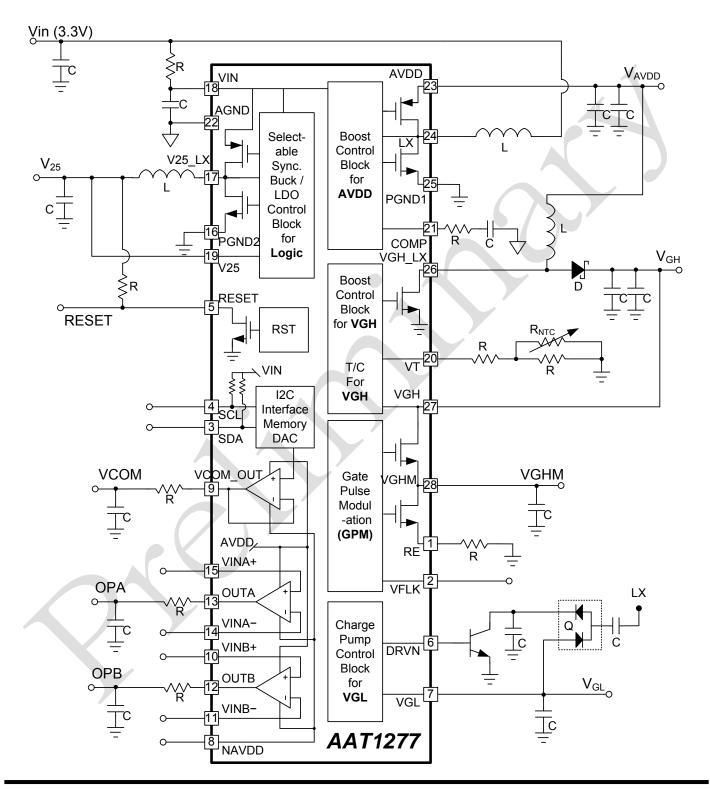
- Advanced Analog Technology, Inc. -

Version 0.03

Page 14 of 44



FUNCTIONAL BLOCK DIAGRAM



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Advanced Analog Technology, Inc. –

Version 0.03

Page 15 of 44



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THEORY OF OPERATION

The AAT1277 offers a complete solution for powering TFT LCD panels. The device integrates two current mode boost regulators, one synchronous boost regulator for the source driver supply, and the second non-synchronous boost regulator with temperature compensation to generate a gate-on voltage for VGH. The AAT1277 also includes a negative charge pump linear regulator for the gate-off voltage, a synchronous buck regulator or a low dropout linear regulator alternatively for system logic power, a gate pulse modulation (GPM) for improving TFT LCD image quality, a XON reset function for input supply monitor, a unity-gain Buffer for VCOM calibrator and two operational amplifiers in the device. The device includes various system protection schemes such as soft start, power up sequencing, fault protection, and thermal shutdown. The AAT1277 also includes I²C interface for various device settings such as output voltages, switching frequency, soft start time, delay time, etc.

Under Voltage Lockout (UVLO)

For systematic startup, AAT1277 employs a UVLO rising threshold of 2.35V typical. Thus, the input supply must exceed the UVLO threshold for the regulators to begin switching. Likewise, the device shuts down all functions when the input voltage is lower than UVLO falling threshold of 2.20V. A 150mV hysteresis is added to prevent device chattering when the input supply is noisy or unstable during power up or power down.

Boost Regulator for AVDD

The synchronous AVDD boost converter integrates a low R_{DSON} (typical 0.2 Ω) NMOS for the low side switch, and a PMOS as the output rectifier. The boost output voltage, over current protection (OCP) threshold, soft start time, switching ON/OFF transient slew rate, and switching frequency are programmed via I²C interface.

The output voltage can be set from 3.6V to 12.7V with a step resolution of 0.1V. Over current protection (OCP) threshold ranges from 1A to 2A with 1A steps, soft start

AAT1277

time can be set from 20ms to 80ms with 20ms steps, and the LX switching ON/OFF transient slew rate can be set from 0.5V/ns to 1.1V/ns with 0.2V/ns steps. The LX switching frequency can be programmed for either 600kHz, 800kHz, 1000kHz, or 1.2MHz. The boost regulator operates from a minimum input voltage of 2.5V, and delivers an output voltage that reaches the maximum capable duty cycle. The duty cycle (D) is calculated by

$$D = \frac{V_O - V_I}{V_O}$$
 or $\frac{V_O}{V_I} = \frac{1}{1 - D}$

where V_O (V_{AVDD}) is the output of the boost regulator. Typical maximum duty cycle is approximately 80%.

At the heart of the current mode topology are two feedback loops. See the AVDD Boost Regulator Functional Block Diagram Figure 1.

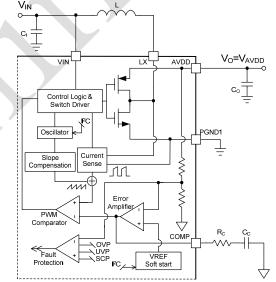


Figure 1. AVDD Boost Regulator Functional Block Diagram

One feedback loop generates a ramp voltage as the inductor current flows through the on resistance of the internal low side power switch. The second loop monitors the boost output via an internal feedback. This feedback voltage is compared to an internal reference voltage using a transconductance error amp. Note that the internal reference voltage is adjusted via I²C control to set the output voltage.

Regulation is achieved by modulating the internal low

Page 16 of 44

Version 0.03



side power switch (NMOS) ON time. During the ON time, the low side NMOS is turned ON to energize the inductor while the high side power switch (PMOS) rectifier is turned OFF. When the NMOS turns off, the PMOS rectifier will turn ON, releasing the inductor energy to regulate the output. The modulating duty cycle is determined by comparing the error amplifier output to the voltage ramp at the non-inverting input of the PWM comparator. Note that this voltage ramp is the sum of the signals generated by the inductor current sense circuitry and the slope compensation circuitry. Slope compensation is added to prevent sub-harmonic oscillations for duty cycles above 50%. During each rising edge of the internal clock pulse, the low side power switch is turned on. The switch is turned off when the voltage ramp generated at the non-inverting input of the PWM comparator exceeds the output voltage of the error amplifier or the voltage at the inverting input of the PWM comparator.

Over Voltage Protection (OVP) for AVDD

When the AVDD boost output exceeds its Over Voltage Protection threshold (typical 15V), the AAT1277 disables the gate driver of this boost regulator and prevents the internal NMOS from switching. Once AVDD voltage falls below the OVP threshold with a hysteresis of approximately 1.25V, the boost will resume switching.

Under Voltage Protection (UVP) for AVDD

When AVDD output voltage drops below its under voltage protection threshold (80% of programmable output voltage) due to overload conditions, an internal fault timer of 160ms is activated. Once activated, if the fault condition surpasses the 160ms, the device will be shutdown. To restart the device, the V_{IN} power must be recycled below the UVLO falling threshold.

Short Circuit Protection (SCP) for AVDD

When AVDD output voltage drops below its short circuit protection threshold (30% of programmable output voltage) due to short circuit conditions, the device will immediately shutdown. This latched condition is reset by toggling $V_{\rm IN}$ power.

Boost Regulator for VGH

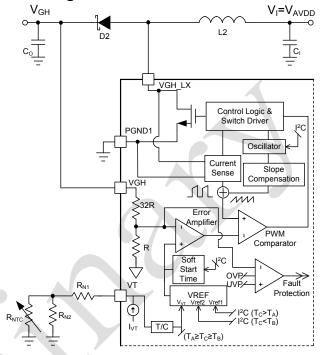


Figure 2. VGH Boost Regulator Functional Block Diagram

The non-synchronous boost regulator that supplies the VGH voltage to the TFT-LCD gate-on voltage also uses a current mode control scheme. Similarly, the output voltage is programmed via I²C interface, and can be set from 10V to 37V with 1V step resolution. The switching frequency of the VGH boost can be set to 400kHz or 800kHz with 400kHz steps and the LX switching ON/OFF transient slew rate can be set from 2.2V/ns to 6.0V/ns with 1.3V/ns steps. The soft start time can be programmed from 4ms to 10ms using 2ms steps.

OVP & UVP for VGH

The VGH boost regulator also includes OVP and UVP. Both protection mechanisms are the same as for AVDD boost regulator, specifically 80% of VGH for UVP and typical 39V of VGH for OVP. UVP has a 160ms delay time to ensure a true UVP condition and a triggered condition latches the device, which can only be reset by recycling VIN power.

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Advanced Analog Technology, Inc. –
Version 0.03
Page 17 of 44



VGH Temperature Compensation

The voltage (V_{NTC}) at VT Pin will adjust the reference voltage at the non-inverting input of the error amplifier. This reference voltage will also adjust the VGH regulation voltage, and therefore tune the output voltage (V_{GH}). The output voltage (V_{GH}) is compensated accordingly. For conditions where the temperature is $T_B \leq T_A \leq T_C$, as show in the temperature compensation for VGH Figure 3, the reference or voltage at NTC is dependent on the voltage (V_{NTC}) at the VT Pin via the following equation:

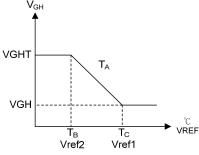


Figure 3. Temperature Compensation for VGH

 $V_{NTC} = I_{NTC} \times \left(R_{N2} + \frac{R_{N1} + R_{NTC}}{R_{N1} \times R_{NTC}} \right)$

Thus, the output voltage V_{GH} will be $V_{GH} = k \times V_{NTC}$

where k = 33 is the internal resistive voltage divider ratio at the non-inverting input of the error amplifier,

If the ambient temperature T_A is below T_B , the V_{GH} voltage will be VGHT, which is set via I^2C and can be set from 25V to 39V with a 1V resolution. Likewise, if T_A is above T_C , the reference generated will be Vref1, and the V_{GH} voltage will be again dependent on the I^2C setting for a range of 15V to 35V. The conditions and equations that determine the V_{GH} voltage are summarized in Table 1.

Table	1
IUNIC	

\v V V	$T_A < T_B$	$T_B{\leq}T_A{\leq}T_C$	$T_A \! > \! T_C$
VREF	Vref2	V _{VT}	Vref1
VGH	VGHT, I ² C Setting	Dependent on external R _{NTC} network	VGH, I ² C Setting

V25 Voltage Selection

The V25 Voltage could be supplied either by the Buck regulator, or LDO determined by the state of BUCK or LDO configuration bit in the CONFIG register.

Buck Regulator for V25

The buck regulator includes a high-side PMOS and a low-side NMOS which eliminate the need for an external Schottky diode. Low on-resistance for both the switches maximizes efficiency. Moreover, the buck is compensated internally so that no external compensation network is required.

The buck output voltage is programmed via I^2C interface, and can be set from 1.5V to 3.0V with 0.1V step resolution. It operates at a fixed switching frequency of 1.2MHz and build in 4ms soft start time.

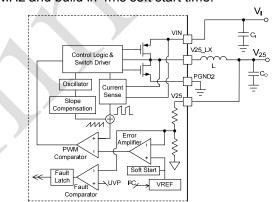


Figure 3. V25 Buck Regulator Functional Block Diagram

The buck regulator also uses the peak current mode PWM control scheme for fast transient response and cycle-by-cycle current limiting. The PWM maintains a constant frequency and varies the duty ratio according to the output voltage and load current. This modulation scheme provides high efficiency at medium to heavy load conditions, and reduces the output ripple at light load conditions. It regulates output voltage from V_{IN} down to an output voltage as low as 1.5V (1.0V). The duty cycle D is calculated by

$$\mathsf{D} = \frac{\mathsf{V}_{\mathsf{O}}}{\mathsf{V}_{\mathsf{I}}} \quad (\mathsf{V}_{\mathsf{O}} = \mathsf{V}_{25})$$

where $V_{\rm O}$ (V_{25}) is the output voltage of the buck regulator.

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Advanced Analog Technology, Inc. –
Version 0.03
Page 18 of 44



Buck Current Limit

The buck regulator includes cycle by cycle current limiting, with a threshold of typically 1.2A. When the current limit threshold is reached, the high side PMOS switch is turned off, releasing the inductive energy.

LDO for V25

The integrated LDO output voltage can be programmed form 1.5V to 3.0V via V25 register and the LDO starts as soon as the supply voltage exceeds the UVLO threshold with 4ms soft-start time, the same time as the buck regulator. The LDO is capable of a minimum 350mA output load.

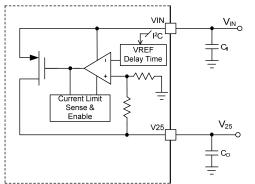


Figure4. V25 LDO Function Block Diagram

UVP for V25

The Buck regulator also includes UVP protection mechanisms. When the buck output drops below the Under Voltage Protection threshold (typical 0.8V), an internal fault timer counter is activated. Once the fault condition surpasses 160ms, the buck and other regulators will be shutdown. To restart the device, the VIN power must be recycled below the UVLO falling threshold.

Negative Charge Pump Linear Regulator for VGL

The AAT1277 integrates a Charge pump controller which drives an external NPN pass transistor to form a linear regulator that receives an input voltage provided by the charge pump, and generates a linear negative supply for the TFT LCD panel gate-off voltage. For the linear regulator to deliver the required output voltage and current, an base-to-emitter resistance $(6.8k\Omega)$ for AAT1277

external NPN pass transistor guarantes a base-drive current. The maximum output voltage capability is determined by the number of charge pump stage, but the actual regulated output voltage is set via I^2C interface. Using a 6 bit resolution, the VGL voltage can be set from -8.0V to -4.5V with 0.1 steps. Typical application uses a single stage, as shown in Figure 5.

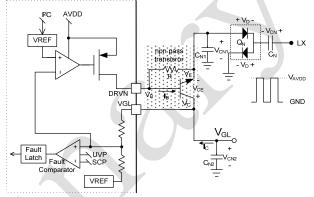


Figure 5. Negative Charge Pump Linear Regulator Functional Block Diagram

When the LX is High (V_{AVDD}), the flying capacitor C_N will charge as the lower diode will turn on and create a path to ground, and $V_{CN}+V_D=V_{AVDD}$. When the LX is Low (GND), the flying capacitor C_N is level shifted in the negative direction, and the node connecting between C_N and Q_N becomes ($-V_{CN}$). Thus, charge will flow from the output C_{N2} to C_N by through the external NPN pass transistor, and the output can be expressed as

 $(-V_{CN})=V_{CN2}-V_{CE}-V_{D} \rightarrow V_{CN2}=(-V_{CN}) + V_{CE} + V_{D}$ $V_{CN2}=(-V_{AVDD})+2V_{D}+V_{CE}$

The voltage magnitude of V_{CE} is controlled by the drive strength of DRVN, which is a p-channel open-drain output. When the NPN pass transistor is fully turned ON, the maximum capable output of this single stage charge pump is approximately $V_{GL}=V_{CN2}=(-V_{AVDD})+0.8V$

where V_{CE}≈0.2V, V_D≈0.3V.

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Advanced Analog Technology, Inc. –
Version 0.03
Page 19 of 44



NPN PASS Transistor

For the linear regulator to deliver the required output voltage and current, the NPN transistor must be properly selected. The transistor's current gain (h_{FE}) limits the guaranteed maximum output current I_C to:

$$I_{C} = h_{FE} \times (I_{B} - \frac{V_{BE}}{R_{BE}})$$

where I_B is the base current, V_{BE} is the bass-to-emitter forward voltage drop, and R_{BE} is the pull-up resistor connected between the transistor's base and emitter. Note that too high of a transistor current gain can destabilize the linear regulator output due to a high loop gain. For the AAT1277, the bias current of the negative linear regulator controller is 0.1mA, therefore, the base-to-emitter resistor should be

 $\mathsf{R}_{\mathsf{BE}} = \frac{\mathsf{V}_{\mathsf{BE}}}{0.1 \mathrm{mA}} = \frac{0.7 \mathrm{V}}{0.1 \mathrm{mA}} \gg 6.8 \mathrm{k}\Omega$

This should provide an output current of at least 50mA.

Other factors such as the transistor saturation voltage at maximum output load current and maximum power dissipation rating of the transistor must be considered when selecting the proper NPN pass transistor.

Charge Pump Flying Capacitors

Use a 0.1μ F ~ 0.47μ F for the flying capacitor (C_N) and make sure that the voltage rating (V_{CN}) of the capacitor is adequate per the number of stages. The voltage rating of the capacitor must satisfy

V_{CN}>n x V_{AVDD}

Where V_{AVDD} is the input supply to the charge pumps, and n is the number of stages per charge pump. Note that the negative charge pump uses 1 stage, i.e. n = 1.

Output Capacitor

The output capacitor of the linear regulator affects the stability of the regulator. To ensure stability, choose an output capacitor in the range of 1μ F ~ 4.7μ F, with low ESR.

Gate Pulse Modulation (GPM)

An internal high voltage switch controller is included for gate pulse modulation which provides gate shaping to improve image quality in TFT LCD applications. The circuitry consist of two high voltage PMOS, one between VGH and VGHM, and another between VGHM and RE. See Figure 6 for the Gate Pulse Modulation Functional Block Diagram.

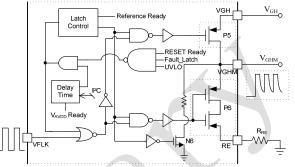


Figure 6. Gate Pulse Modulation Functional Block Diagram

When the switch controller is enabled, logic level on the VFLK input will determine which PMOS switch is ON or OFF. If VFLK is logic High, P5 turns on and P6 turns off, VGHM connects to VGH. If VFLK is logic Low, P5 turns off and P6 turns on, VGHM connects to RE, and the VGHM output (V_{GHM}) is discharged via the resistor connected at RE to ground. Note that the resistor (R_{RE}) value can be adjusted to different discharge time or high to low transient slope rate.

The GPM is enabled only after a set of power ready condition is present. For the GPM to be enabled, the device supply voltage should exceed the UVLO threshold, RESET function must be power on ready, no fault condition is present, and the programmable delayed time, t_{DLY} range from 0ms to 80ms with 20ms step resolution, should have passed after V_{GH} soft start has completed. Note that during the GPM enable period, VGH output will be internally pulled to ground via an internal resistor and NMOS (N6). Once enabled, VFLK input will control the internal switches.

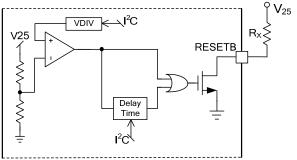
During operation, if the input supply falls below the UVLO threshold, the GPM will be immediately disabled. Instantly, the high side PMOS P5 will turn on, the low side PMOS P6 will turn off simultaneously, and VFLK input will have no control over the PMOS switches.

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Advanced Analog Technology, Inc. –
Version 0.03
Page 20 of 44



RESETB (XAO)

This device has an internal reset circuit to monitor the voltage at V25. When V25 is lower than the detect threshold VDIV, RESET output will be pulled low. RESETB is an open-drain output that needs a pull-up resistor ($R_x = 10k\Omega$) to a system supply. The VDIV is set via I²C from 1.2V to 2.6V with 0.2V step resolution. In typical application, see Figure 7 for RESETB Functional Block Diagram.





When V25 rises above its UVLO threshold (2.35V typ.), V_{HYS_DIVI} , after V25 had finished ramp, the output will be pulled High after t_{RST} delay time has completed. The t_{RST} delay time ranges from 0ms to 30ms with 2ms step resolution and also can be set via I^2C . See Figure 8 for RESETB Operation Timing Chart

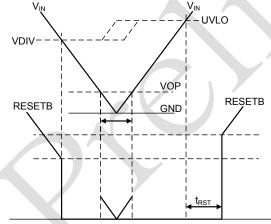


Figure 8. RESETB Operation Timing Chart

Programmable VCOM Buffer

The I²C programmable VCOM operation amplifier can be used to digitally adjust a panel's VCOM voltage to remove flicker.

AAT1277

The VCOM voltage calibration needs two steps for adjustment. First step is to set the central value of VCOM voltage according to the V_{AVDD} , V_{GH} , and LCD panel characteristic. The VCOM voltage is programmable from 0.8V to 5.1V or -4.1V to +0.2V by VCOM register. The first step is normally done in PCB assembly manufacture.

Second step is to calibrate the VCOM voltage on the LCD panel assembly line by VCOM RAM register through I²C digital interface. The VCOM register value indicates the voltage increment or decrement of VCOM_OUT which is preset by V_{COM}. Once the proper value is identified, the V_{COM} register value can be renewed with VCOM register value added. The default value for VCOM register is 1,000,000. If 100,0001 is written into VCOM register, the V_{COM} value will increase with one DAC step. In the other hand if 0111,111 is written to VCOM register, the V_{COM} will decrease with one DAC step.

The VCOM voltage also supports temperature compensation and allows its output voltage to transition from a lower voltage at low temperatures V_{COMT} to a higher voltage at high temperatures V_{COM}. The output voltage with temperature compensation is decided by voltage at the VT pin. The thermistor network formed by R1, R2, and RNTC generates a voltage at the VT pin whose value decreases with increasing temperature. With proper selection of the external components RNTC, R1, and R2, temperatures THOT and TCOLD can be configured to suit each display's characteristics. The temperature compensation resolution is 6 Bits. The temperature compensation for VCOM could be turn on/off by bit VCOMT in register CONFIG. If temperature compensation for VCOM is ON state, both V_{COM} and V_{COMT} need to be input. Otherwise only V_{COM} is active for VCOM voltage setting without temperature compensation.

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Advanced Analog Technology, Inc. –
Version 0.03
Page 21 of 44



Advanced Analog Technology, Inc.

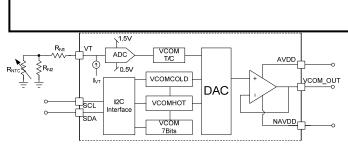


Figure 9. PVCOM Function Block

Operational Amplifiers

There are two operational amplifiers in the device. Both of them are capable of rail-to-rail input and output, ±120mA output short-circuit current, and a 12V/µs slew rate. The positive and negative supplies of operational amplifiers are connected to the AVDD pin and NAVDD pin individually. For minimize the power consumption, setting the OPA_A bit or OPA_B bit in CONFIG register can turn on or off operational amplifier individually.

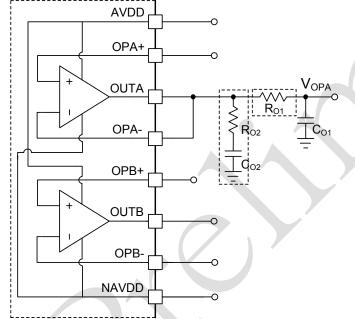


Figure 10. Operational Amplifier Functional Block Diagram

In the unity-gain configuration, the capacitive load adds a pole to the loop gain that impacts the stability of the system and leads to output peaking, ringing and oscillation. A higher pole frequency results in greater stability. In fact, if the pole frequency is lower than or close to the unity gain frequency, the pole can have a significant negative impact on phase and gain margins.

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Advanced Analog Technology, Inc. –
Version 0.03
Page 22 of 44

AAT1277

Therefore, the stability decreases when the capacitive load increases.

One method of improving capacitive load drive is to insert a 2Ω to 20Ω resistor (R₀₁) in series with the output, as shown in Figure 6. This reduces ringing with large capacitive loads while maintaining DC accuracy.

Another method for improving transient response is to add a snubber circuit at the output. A snubber circuit consists of a resistor (R_{O2}) in series with a capacitor (C_{O2}), which improves output settling time and reduces peaking. The advantage of this topology is that it draws no DC current nor does it reduce the gain.

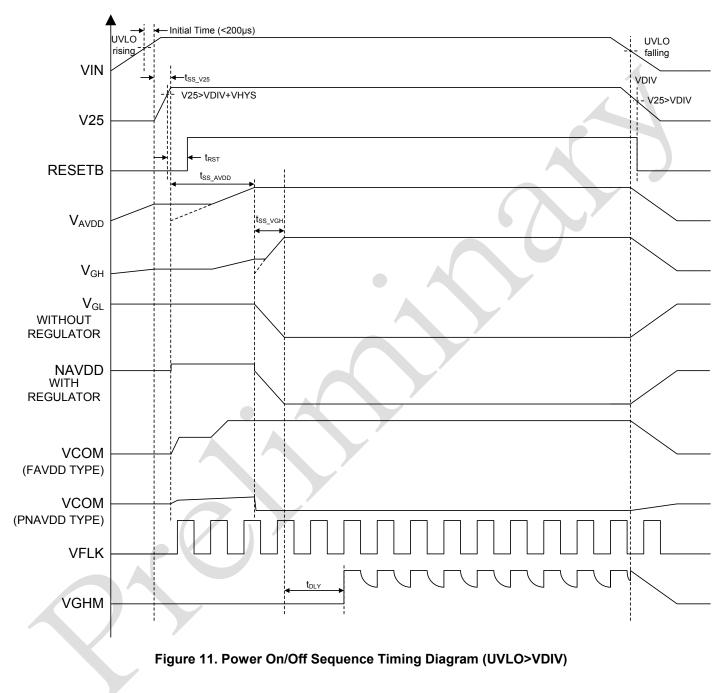
Thermal Shutdown

The AAT1277 device enters into fault protection shutdown when the junction temperature reaches approximately 150°C. To restart the device when the junction temperature has fallen below the thermal shutdown threshold, recycle the device supply power below the UVLO falling threshold.



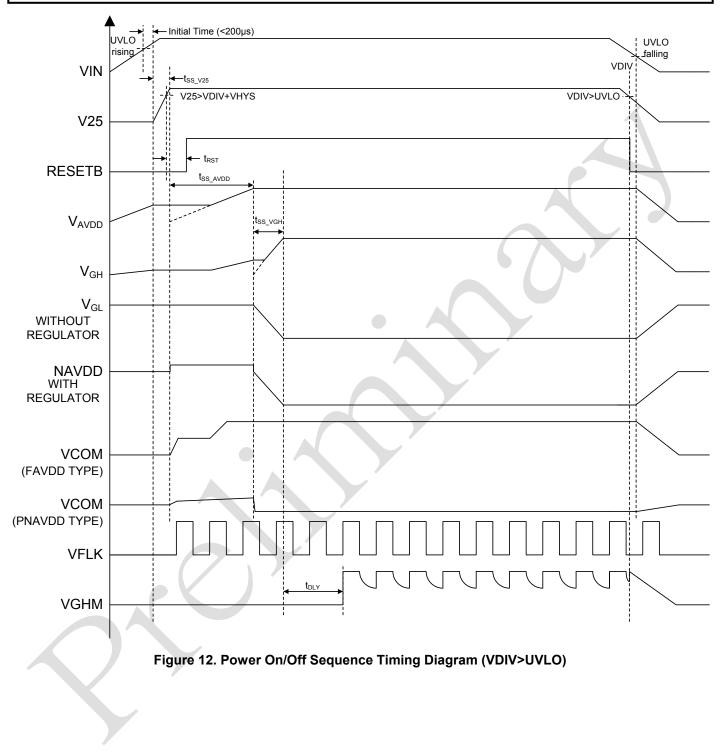
Power On/Off Sequence

The AAT1277 Power On/Off Sequence is as shown in Figure 11 and Figure 12.



- 台灣類比科技股份有限公司 –
Advanced Analog Technology, Inc. –
Version 0.03
Page 23 of 44







Advanced Analog Technology, Inc.

AAT1277

I²C Serial Interface

The AAT1277 features an I^2C -compatible, 2-wire serial interface consisting of a SDA and a SCL. SDA and SCL are an I/O with an open-drain output that requires a pull up resistor to realize high-logic levels. Pull up resistor values should be chosen to ensure that the rise and fall times are within specification. A typical value for the pull up resistors is 4.7k Ω . Each slave on the I^2C bus responds to a slave address byte sent immediately following a Start Condition. Below diagram shows the definition of timing on I^2C bus:

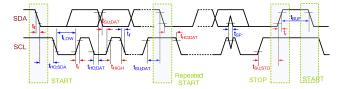
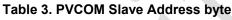


Figure 13. Definition of timing on I²C bus

The slave address byte contains the slave address in the most significant 7 bits and the R/W bit in the least significant bit. The AAT1277 consist of two slave addresses, one slave address for accessing the PVCOM, the other slave address for accessing the PMIC section (Power Management Integrated Circuit). Below diagram shows the two slave addresses:

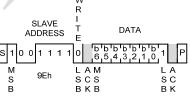


1	0	0	1	1	1	7	R/W
MSB							LSB
Table 4 PMIC Slave Address byte							
1	1	1	0	1	0	0	R/W
MSB							LSB

I²C Protocol for PVCOM

When the R/W bit is 0 (such as in 9Eh), the master is indicating it will write data to the slave. If R/W = 1 (9Fh in this case), the master is indicating it wants to read from the slave. During an I2C write operation, the master must transmit a register address to identify the memory location where the slave is to store the data.

A master device writes data to DR (DAC Register) by the following timing diagram.



A master device writes data to DR (DAC Register) and EE (EEPROM) by the following timing diagram.

	SLAVE DDRESS	I T E	DATA
S 1 0 0	1 1 1	10 ^{bb} 65	b'b'b'b'b 4,3,2,1,0,0 P
M S B	9Eh	L A M S C S B K B	L A S C B K

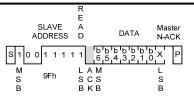
A master reading data from EE by the following timing diagram: (then DR = EE)

- 台灣類比科技股份有限公司 –
Advanced Analog Technology, Inc. –
Version 0.03
Page 25 of 44



Advanced Analog Technology, Inc.

AAT1277



S: Start Condition, P: Stop Condition, X : Don't Care.

□: Master to Slave, □:Slave to Master

I²C Protocol for PMIC

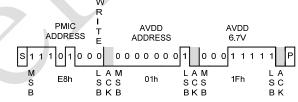
When the R/W bit is 0 (such as in E8h), the master is indicating it will write data to the slave. If R/W = 1 (E9h in this case), the master is indicating it wants to read from the slave. During an I2C write operation, the master must transmit a register address to identify the memory location where the slave is to store the data. The register address is always the second byte transmitted during a write operation following the slave address byte. The AAT1277 PMIC register addresses refer to the I2C register map.

During power-up, the values stored in the EE (EEPROM, nonvolatile memory) are recalled into the DR (DAC Register, volatile memory).

WRITE OPERATION

Write Single Byte To DR (DAC Register):

- Step 1: Master sends Start Condition.
- Step 2: Master sends the value E8h. (the AAT1277 PMIC address 1110100b and R/W bit = Low) AAT1277 will acknowledge a bit for this byte.
- Step 3: Send DR address (ex.01h, address of AVDD)
 - AAT1277 will acknowledge a bit for this byte.
- Step 4: Send the data to be written to the DR (ex.1Fh, VCC = 6.7V) AAT1277 will acknowledge a bit for this byte.
- Step 5: Master sends Stop Condition.
- Example: Writing 1Fh (6.7V) to the DR address 01h (AVDD)



Write Multiple Bytes To DR (DAC Register):

- Step 1: Master sends Start Condition.
- Step 2: Master sends the value E8h. (The AAT1277 PMIC address 1110100b and R/W bit = Low) AAT1277 will acknowledge a bit for this byte.
- Step 3: Send DR address (ex.06h, address of VGL)
 - AAT1277 will acknowledge a bit for this byte.
- Step 4: Send the data to be written to the DR (ex.0Fh, VGL=-6V) AAT1277 will acknowledge a bit for this byte.
- Step 5: Master continues sending the other bytes to be written to the DRs. AAT1277 will acknowledge a bit for each byte and DR address will automatically increase.

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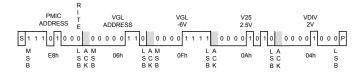
Version 0.03

Page 26 of 44



Step 6: Master sends Stop Condition.

Example: Writing 0Fh(-6V), 0Ah(2.5V), 04h(2V) to the DR address 06h, 07h, 08h (VGL, V25, VDIV)

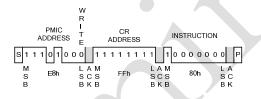


Write All DR (DAC Register) Data To EE (EEPROM):

- Step 1: Master sends Start Condition.
- Step 2: Master sends the value E8h. (the AAT1277 PMIC address 1110100b and R/W bit = Low) AAT1277 will acknowledge a bit for this byte.
- Step 3: Send CR (Control Register) address (FFh)

AAT1277 will acknowledge a bit for this byte.

- Step 4: Send the instruction 1000000b (X: Don't care, ex. 80h) to make duplicate data from DR to EE. AAT1277 will acknowledge a bit for this byte.
- Step 5: Master sends Stop Condition.
- Example: Writing all DR data to EE.



READ OPERATION

Read Single Data From DAC Register (DR):

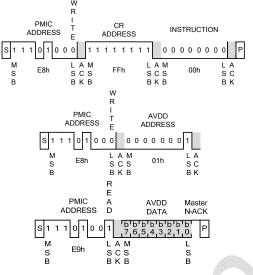
- Step 1: Master sends Start Condition.
- Step 2: Master sends the value E8h. (the AAT1277 PMIC address 1110100b and R/W bit = Low) AAT1277 will acknowledge a bit for this byte.
- Step 3: Send Control Register (CR) address (FFh) AAT1277 will acknowledge a bit for this byte.
- Step 4: Send the instruction 0000000b (X: Don't care, ex. 00h) to specify that the data is read from the DR. AAT1277 will acknowledge a bit for this byte.
- Step 5: Master sends Stop Condition.
- Step 6: Master sends Start Condition.
- Step 7: Master sends the value E8h. (The AAT1277 PMIC address 1110100b and R/W bit = Low) AAT1277 will acknowledge a bit for this byte.
- Step 8: Send specified DR address to be read (ex.05h, address of AVDD) AAT1277 will acknowledge a bit for this byte.
- Step 9: Master sends Start Condition (Repeated Start Condition, instead of Stop Condition)
- Step 10: Master sends the value E9h. (the AAT1277 PMIC address 1110100b and R/W bit = High) AAT1277 will acknowledge a bit for this byte.
- Step 11: Master read the data from DR and not-acknowledges for this byte.
- Step 12: Master sends Stop Condition.

- 台灣類比科技股份有限公司 –
Advanced Analog Technology, Inc. –
Version 0.03

Page 27 of 44



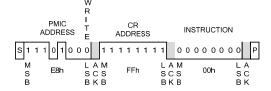
Example: Reading data from the DR addresses 01h (AVDD)



Read Multiple Data From DAC Register (DR):

- Step 1: Master sends Start Condition.
- Step 2: Master sends the value E8h. (The AAT1277 PMIC address 1110100b and R/W bit = Low) AAT1277 will acknowledge a bit for this byte.
- Step 3: Send Control Register (CR) address (FFh) AAT1277 will acknowledge a bit for this byte.
- Step 4: Send the instruction 0XXXXXX0b (X: Don't care, ex. 00h) to specify that the data is read from the DR. AAT1277 will acknowledge a bit for this byte.
- Step 5: Master sends Stop Condition.
- Step 6: Master sends Start Condition.
- Step 7: Master sends the value E8h. (The AAT1277 PMIC address 1110100b and R/W bit = Low) AAT1277 will acknowledge a bit for this byte.
- Step 8: Send specified DR address to be read (ex.05h, address of AVDD) AAT1277 will acknowledge a bit for this byte.
- Step 9: Master sends Start Condition (Repeated Start Condition, instead of Stop Condition)
- Step 10: Master sends the value E9h. (The AAT1277 PMIC address 1110100b and R/W bit = High) AAT1277 will acknowledge a bit for this byte.
- Step 11: Master continues read the data from DR and acknowledges a bit for each byte. But, master not-acknowledges after received the last reading data. The DR address will automatically increase.
- Step 12: Master sends Stop Condition.

Example: Reading data from the DR addresses 06h, 07h, 08h (VGL, V25, VDIV)

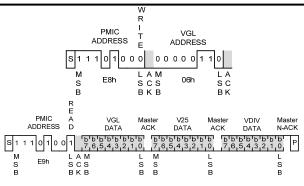


- 台灣類比科技股份有限公司 –
Advanced Analog Technology, Inc. –
Version 0.03
Page 28 of 44



Advanced Analog Technology, Inc.

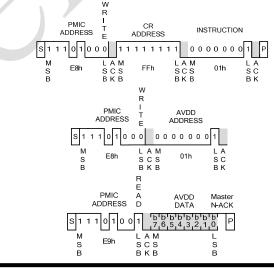
AAT1277



Read Single Data From EEPROM (EE):

- Step 1: Master sends Start Condition.
- Step 2: Master sends the value E8h. (The AAT1277 PMIC address 1110100b and R/W bit = Low) AAT1277 will acknowledge a bit for this byte.
- Step 3: Send Control Register (CR) address (FFh)
 - AAT1277 will acknowledge a bit for this byte.
- Step 4: Send the instruction 0XXXXX1b (X: Don't care, ex. 01h) to specify that the data is read from the EE. AAT1277 will acknowledge a bit for this byte.
- Step 5: Master sends Stop Condition.
- Step 6: Master sends Start Condition.
- Step 7: Master sends the value E8h. (The AAT1277 PMIC address 1110100b and R/W bit = Low)
 - AAT1277 will acknowledge a bit for this byte.
- Step 8: Send specified EE address to be read (ex.01h, address of AVDD) AAT1277 will acknowledge a bit for this byte.
- Step 9: Master sends Start Condition (Repeated Start Condition, instead of Stop Condition)
- Step 10: Master sends the value E9h. (The AAT1277 PMIC address 1110100b and R/W bit = High)
 - AAT1277 will acknowledge a bit for this byte.
- Step 11: Master read the data from EE and not-acknowledges for this byte.
- Step 12: Master sends Stop Condition.

Example: Reading data from the EE addresses 01h (AVDD)



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- Advanced Analog Technology, Inc. -

Version 0.03

Page 29 of 44



Advanced Analog Technology, Inc.

AAT1277

Read Multiple Data From EEPROM (EE):

Step 1: Master sends Start Condition.

Step 2: Master sends the value E8h. (The AAT1277 PMIC address 1110100b and R/W bit = Low) AAT1277 will acknowledge a bit for this byte.

Step 3: Send Control Register (CR) address (FFh)

AAT1277 will acknowledge a bit for this byte

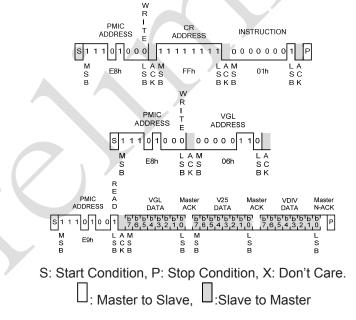
- Step 4: Send the instruction 0XXXXX1b (X: Don't care, ex. 01h) to specify that the data is read from the EE. AAT1277 will acknowledge a bit for this byte.
- Step 5: Master sends Stop Condition.
- Step 6: Master sends Start Condition.
- Step 7: Master sends the value E8h. (The AAT1277 PMIC address 1110100b and R/W bit = Low) AAT1277 will acknowledge a bit for this byte.
- Step 8: Send specified EE address to be read (ex.03h, address of AVDD) AAT1277 will acknowledge a bit for this byte.
- Step 9: Master sends Start Condition (Repeated Start Condition, instead of Stop Condition)
- Step 10: Master sends the value E9h. (The AAT1277 PMIC address 1110100b and R/W bit = High)

AAT1277 will acknowledge a bit for this byte.

Step 11: Master continues read the data from EE and acknowledges a bit for each byte. But, master not-acknowledges after received the last reading data. The EE address will automatically increase.

Step 12: Master sends Stop Condition.

Example: Reading data from the EE addresses 06h, 07h, 08h (VGL, V25, VDIV)

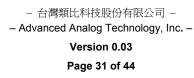


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Advanced Analog Technology, Inc. –
Version 0.03
Page 30 of 44



PMIC I2C INTERFACE REGISTER DESCRIPTION

REGISTER ADDRESS	REGISTER NAME	FACTORY DEFAULT	DESCRIPTION
00h	CONFIG	73h	Sets function control bits
01h	AVDD	31h	Sets the output voltage of AVDD boost converter
02h	AVDDCONFIG	4Fh	Sets miscellaneous configuration bits for AVDD boost converter
03h	VGH	0Dh	Sets the output voltage of VGH boost converter at high temperatures (VGHT = 0) or VGH boost converter (VGHT=1)
04h	VGHT	14h	Sets the output voltage of VGH boost converter at low temperatures (VGHT=0)
05h	VGHCONFIG	03h	Sets miscellaneous configuration bits for VGH boost converte
06h	VGL	0Fh	Sets the output voltage of VGL linear regulator
07h	V25	0Ah	Sets the output voltage of buck converter
08h	VDIV	04h	Sets the threshold of the /RST signals
09h	RESETB	06h	Sets the resetb pulse duration
0Ah	DLY	01h	Sets the gate voltage shaping delay
0Bh	VCOM	57h	Presets the output voltage of VCOM reference at high temperatures (VCOMT = 0) or VCOM reference (VCOMT=1)
0Ch	VCOMT	52h	Presets the output voltage of VCOM reference at low temperatures (VCOMT=0)
FFh	Control	00h	Controls whether read and write operations access RAM or EEPROM registers





PMIC DAC REGISTER SETTING DESCRIPTION

CONFIG (00h)

Bit7	Bit 6	Bit 5	Bit4	Bit3	Bit2	Bit1	Bit0
VCOMR	VCOMT	OPA_B	OPA_A	BUCK/LDO	VGL	VGHT	VGH

	Bits	This bit enables/disables the boost converter for VGH voltage regulator.
VGH	Dito	
VGIT	0	
		1 Disables the VGH boot converter
	Bits	This bit enables/disables the temperature compensation for VGH regulator.
VGHT	1	0 Enables the temperature compensation for VGH voltage regulator
	1	1 Disables the temperature compensation for VGH voltage regulator
	Bits	This bit enables/disables the VGL linear voltage regulator.
VGL	0	0 Enables the VGL linear voltage regulator
	2	1 Disables the VGL linear voltage regulator
	Bits	his bit selects the operation mode for V25 voltage regulator.
BUCK/LDO	3	0 Selects the Buck converter for V25 voltage regulator
		1 Selects the LDO for V25 voltage regulator
	Bits	This bit enables/disables the OPA_A operational amplifier.
OPA_A		0 Enables the OPA_A operational amplifier
	4	1 Disables the OPA_A operational amplifier
	Bits	This bit enables/disables the OPA_B operational amplifier.
OPA_B	_	0 Enables the OPA_B operational amplifier
	5	1 Disables the OPA_B operational amplifier
	Bits	This bit enables/disables the temperature compensation for VCOM voltage
VCOMT		0 Enables the temperature compensation for VCOM voltage
	6	1 Disables the temperature compensation for VCOM voltage
	Bits	This bit select the AVDD boost current limite value
VCOMR	_	0 This bit sets the V COM voltage output range
	7	1 V COM = -4V~0.8V for PN AVDD Application



AVDD (01h)

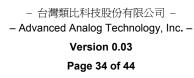
Bit7	Bit 6	Bit 5	Bit4	Bit3	Bit2	Bit1	Bit0
Reserved				V _{AVDD}			
L							
0000000	V _{AVDD} =3.6V	0011010	V _{AVDD} =6.2V	0110100	V _{AVDD} =8.8V	1001110	V _{AVDD} =11.4V
0000001	V _{AVDD} =3.7V	0011011	V _{AVDD} =6.3V	0110101	V _{AVDD} =8.9V	1001111	V _{AVDD} =11.5V
0000010	V _{AVDD} =3.8V	0011100	V _{AVDD} =6.4V	0110110	V _{AVDD} =9.0V	1010000	V _{AVDD} =11.6V
0000011	V _{AVDD} =3.9V	0011101	V _{AVDD} =6.5V	0110111	V _{AVDD} =9.1V	1010001	V _{AVDD} =11.7V
0000100	V _{AVDD} =4.0V	0011110	V _{AVDD} =6.6V	0111000	V _{AVDD} =9.2V	1010010	V _{AVDD} =11.8V
0000101	V _{AVDD} =4.1V	0011111	V _{AVDD} =6.7V	0111001	V _{AVDD} =9.3V	1010011	V _{AVDD} =11.9V
0000110	V _{AVDD} =4.2V	0100000	V _{AVDD} =6.8V	0111010	V _{AVDD} =9.4V	1010100	V _{AVDD} =12.0V
0000111	V _{AVDD} =4.3V	0100001	V _{AVDD} =6.9V	0111011	V _{AVDD} =9.5V	1010101	V _{AVDD} =12.1V
0001000	V _{AVDD} =4.4V	0100010	V _{AVDD} =7.0V	0111100	V _{AVDD} =9.6V	1010110	V _{AVDD} =12.2V
0001001	V _{AVDD} =4.5V	0100011	V _{AVDD} =7.1V	0111101	V _{AVDD} =9.7V	1010111	V _{AVDD} =12.3V
0001010	V _{AVDD} =4.6V	0100100	V _{AVDD} =7.2V	0111110	V _{AVDD} =9.8V	1011000	V _{AVDD} =12.4V
0001011	V _{AVDD} =4.7V	0100101	V _{AVDD} =7.3V	0111111	V _{AVDD} =9.9V	1011001	V _{AVDD} =12.5V
0001100	V _{AVDD} =4.8V	0100110	V _{AVDD} =7.4V	1000000	V _{AVDD} =10.0V	1011010	V _{AVDD} =12.6V
0001101	V _{AVDD} =4.9V	0100111	V _{AVDD} =7.5V	1000001	V_{AVDD} =10.1V	1011011	V _{AVDD} =12.7V
0001110	V _{AVDD} =5.0V	0101000	V _{AVDD} =7.6V	1000010	V_{AVDD} =10.2V	Others	V _{AVDD} =12.7V
0001111	V _{AVDD} =5.1V	0101001	V _{AVDD} =7.7V	1000011	V_{AVDD} =10.3V		
0010000	V _{AVDD} =5.2V	0101010	V _{AVDD} =7.8V	1000100	V_{AVDD} =10.4V		
0010001	V _{AVDD} =5.3V	0101011	V _{AVDD} =7.9V	1000101	V _{AVDD} =10.5V		
0010010	V _{AVDD} =5.4V	0101100	V _{AVDD} =8.0V	1000110	V _{AVDD} =10.6V		
0010011	V _{AVDD} =5.5V	0101101	V _{AVDD} =8.1V	1000111	V_{AVDD} =10.7V		
0010100	V _{AVDD} =5.6V	0101110	V _{AVDD} =8.2V	1001000	V_{AVDD} =10.8V		
0010101	V _{AVDD} =5.7V	0101111	V _{AVDD} =8.3V	1001001	V_{AVDD} =10.9V		
0010110	V _{AVDD} =5.8V	0110000	V _{AVDD} =8.4V	1001010	V _{AVDD} =11.0V		
0010111	V _{AVDD} =5.9V	0110001	V _{AVDD} =8.5V	1001011	V _{AVDD} =11.1V		
0011000	V _{AVDD} =6.0V	0110010	V _{AVDD} =8.6V	1001100	V _{AVDD} =11.2V		
0011001	V _{AVDD} =6.1V	0110011	V _{AVDD} =8.7V	1001101	V _{AVDD} =11.3V		



AVDDCONFIG (02h)

Bit7	Bit 6	Bit 5	Bit4	Bit3	Bit2	Bit1	Bit0
Reserved	I _{LIM_LX}	t _{ss_avdd}		f _{osc_}	AVDD	TS	S _{LX}

	Bits	These	bits configure the rising and falling speed of AVDD boost switch.					
		00	Tf = 0.5 V/ns Tr = 0.5 V/ns					
TS_{LX}	[1:0]	01	Tf = 0.7 V/ns Tr = 0.7 V/ns					
	[1:0]	10	Tf = 0.9 V/ns Tr = 0.9 V/ns					
		11	Tf = 1.1 V/ns Tr = 1.1 V/ns					
	Bits	These	bit configure the switching frequency of AVDD boost.					
	[3:2]	00	f _{OSC_AVDD} = 600 kHz					
f _{OSC_AVDD}		01	f _{OSC_AVDD} = 800 kHz					
		10	f _{OSC_AVDD} = 1000 kHz					
		11	f _{OSC_AVDD} = 1200 kHz					
	Bits	These	pits configure the soft start duration for AVDD boost regulator					
		00	t _{ss_AVDD} = 20 ms					
t_{SS_AVDD}	[5:4]	01	t _{ss_AVDD} = 40 ms					
	[3.4]	10	t _{ss_AVDD} = 60 ms					
		11	t _{ss_AVDD} = 80 ms					
	Bits	This bit	selects the AVDD boost current limit value					
I _{LIM_LX}	[6]	0	$I_{\text{LIM}_{\text{LX}}} = 1A$					
	[0]	1	I _{LIM_LX} = 2A					





Bit7	Bit 6	Bit 5	Bit4	Bit3	Bit2	Bit1	Bit0
Reserved					V_{GH}		
	00	0000	V _{GH} = 10V	01111	V _{GH} = 25	V	
	00	0001	V _{GH} = 11V	10000	V _{GH} = 26 ^v	V	
	00	0010	V _{GH} = 12V	10001	V _{GH} = 27	v	
	00	0011	V _{GH} = 13V	10010	V _{GH} = 28 ^v	V	
	00	0100	V _{GH} = 14V	10011	V _{GH} = 29 ^v	V	,
	00	0101	V _{GH} = 15V	10100	V _{GH} = 30 ^v		
	00	0110	V _{GH} = 16V 10101		V _{GH} = 31V		
	00	0111	V _{GH} = 17V	10110	V _{GH} = 32V		
	01	1000	V _{GH} = 18V	10111	V _{GH} = 33V	V	
	01	1001	V _{GH} = 19V	11000	V _{GH} = 34	V	
	01	1010	V _{GH} = 20V	11001	V _{GH} = 35 ^v	V	
	01	1011	V _{GH} = 21V	11010	V _{GH} = 36 ^v	V	
	01	1100	V _{GH} = 22V	11011	V _{GH} = 37	V	
	01	1101	V _{GH} = 23V	Others	V _{GH} = 37	V	
	0	1110	V _{GH} = 24V	×			



Bit7	Bit 6	Bit 5	Bit4	Bit3	Bit2	Bit1	Bit0	
	Reserved			V _{GHT}				
	00	0000	V _{GHT} = 10V	01111	V _{GHT} = 25	5V		
	00	0001	V _{GHT} = 11V	10000	V _{GHT} = 26	3V		
	00	0010	V _{GHT} = 12V	10001	V _{GHT} = 27	7V		
	00	0011	V _{GHT} = 13V	10010	V _{GHT} = 28	BV		
	00	0100	V _{GHT} = 14V	10011	V _{GHT} = 29V		,	
	00	0101	V _{GHT} = 15V	10100	V _{GHT} = 30	VV		
	00	0110	V _{GHT} = 16V	10101	V _{GHT} = 31	IV		
	00	0111	V _{GHT} = 17V	10110	V _{GHT} = 32	2V		
	0	1000	V _{GHT} = 18V	10111	V _{GHT} = 33	₿V		
	0	1001	V _{GHT} = 19V	11000	V _{GHT} = 34	ŧV		
	0	1010	V _{GHT} = 20V	11001	11001 V _{GHT} = 35V			
	0	1011	V _{GHT} = 21V	11010	V _{GHT} = 36	3V		
	0	1100	V _{GHT} = 22V	11011	V _{GHT} = 37	″V		
	01	1101	V _{GHT} = 23V	Others	V _{GHT} = 37	′ ∨		
	0	1110	V _{GHT} = 24V					



VGHCONFIG (05h)

Bit7	Bit 6	Bit 5	Bit4	Bit3	Bit2	Bit1	Bit0
Rese	Reserved			VGHC	ONFIG		

	Bits	These	bits configure the rising and falling speed of VGH boost switch.
		00	Tf = 2.2 V/ns Tr = 2.25 V/ns
TS_{VGH}	[1:0]	01	Tf = 3.5 V/ns Tr = 3.5 V/ns
	[1.0]	10	Tf = 4.8 V/ns Tr = 4.8 V/ns
		11	Tf = 6.0 V/ns Tr = 6.0 V/ns
	Bits	These	bits configure the soft start duration for VGH boost regulator
		00	t _{SS_VGHL} = 4 ms
t_{SS_VGHL}	[0.0]	01	t _{SS_VGHL} = 6 ms
	[3:2]	10	t _{SS_VGHL} = 8 ms
		11	t _{SS_VGHL} = 10 ms
	Bits	This bit	select the VGH boost current limite value
f _{osc_vgн}	[4]	00	f _{OSC_VGH} = 400 kHz
	[4]	01	f _{OSC_VGH} = 800 kHz



Bit7	Bit 6	Bit 5	Bit4	Bit3	Bit2	Bit1	Bit	
Reserved		VGL						
		0000	V _{GL} = -4.5V	010011	V _{GL} = -6.4V			
		0001	V _{GL} = -4.6V	010100	V _{GL} = -6.5\			
	00	0010	V_{GL} = -4.7V	010101	V _{GL} = -6.6\	/		
	00	0011	V _{GL} = -4.8V	010110	V _{GL} = -6.7∖	/		
	00	0100	V_{GL} = -4.9V	010111	V _{GL} = -6.8V	/		
	00	0101	V_{GL} = -5.0V	011000	V _{GL} = -6.9∖			
	00	0110	V _{GL} = -5.1V	011001	V _{GL} = -7.0∖			
	00	0111	V _{GL} = -5.2V	011010	V _{GL} = -7.1V			
	00	1000	V _{GL} = -5.3V	011011	V _{GL} = -7.2V	1		
	00	1001	V _{GL} = -5.4V	011100	V _{GL} = -7.3V	/		
	00	1010	V _{GL} = -5.5V	011101	V _{GL} = -7.4V	/		
	00	1011	V _{GL} = -5.6V	011110	V _{GL} = -7.5V	/		
	00	1100	V _{GL} = -5.7V	011111	V _{GL} = -7.6V	/		
	00	1101	V _{GL} = -5.8V	100000	V _{GL} = -7.7V	/		
	00	1110	V _{GL} = -5.9V	100001	V _{GL} = -7.8\	/		
	00	1111	$V_{GL} = -6.0V$	100010	V _{GL} = -7.9∖	/		
	01	0000	V _{GL} = -6.1V	100011	V _{GL} = -8.0V	/		
	01	0001	V _{GL} = -6.2V	Others	V _{GL} = -8.0\	/		
	01	0010	$V_{GL} = -6.3V$		-			



November 2015

AAT1277

25 (07h)								
Bit7	Bit 6	Bit 5	Bit4	Bit3	Bit2	Bit1	Bit0	
	Rese	erved		V ₂₅				
		000	1 5 \/	1000	<u> </u>	/		
			$V_{25} = 1.5 V$ $V_{25} = 1.6 V$	1000	$V_{25} = 2.3$ $V_{25} = 2.4$ V_{2			
			V ₂₅ = 1.7 V	1010	V ₂₅ = 2.5 V			
	0	011	V ₂₅ = 1.8 V	1011	V ₂₅ = 2.6 V			
	0	100	V ₂₅ = 1.9 V	1100	V ₂₅ = 2.7 V			
	0	101	V ₂₅ = 2.0 V	1101	V ₂₅ = 2.8 V			
	0	110	V ₂₅ = 2.1 V	1110	V ₂₅ = 2.9 V	/		
	0	111	V ₂₅ = 2.2 V	1111	V ₂₅ = 3.0 V	/		

VDIV (08h)

Bit7	Bit 6	Bit 5	Bit4	Bit3	Bit2	Bit1	Bit0
		Reserved				VDIV	

000	VDIV = 1.2 V
001	VDIV = 1.4 V
010	VDIV = 1.6 V
011	VDIV = 1.8 V
100	VDIV = 2.0 V
101	VDIV = 2.2 V
110	VDIV = 2.4 V
111	VDIV = 2.6 V



RESETB (09h)

Bit7	Bit 6	Bit 5	Bit4	Bit3	Bit2	Bit1	Bit0	
	Rese	erved		RESETB				
								
	0000 t _{RST} = 0		_{RST} = 0 ms	1000	t _{RST} = 16 n	ns		
	0			1001	t _{RST} = 18 n	ns		
	0			1010	t _{RST} = 20 n	ns		
	0			1011	t _{RST} = 22 n	ns		
	0	100 t _i	_{RST} = 8 ms	1100	t _{RST} = 24 n	ns		
	0	101 t _R	_{st} = 10 ms	1101	t _{RST} = 26 ms			
	0	0110 t _{RST} = 12 ms		1110	t _{RST} = 28 n	ns		
	0	111 t _R	_{st} = 14 ms	1111	t _{RST} = 30 n	ns		

DLY (0Ah)

Bit7	Bit 6	Bit 5	Bit4	Bit3	Bit2	Bit1	Bit0
		Rese	erved	\sim		DI	LY

_		
	00	t _{DLY} = 0 ms
	01	t _{DLY} = 20 ms
	10	t _{DLY} = 40 ms
	11	t _{DLY} = 60 ms
-		



Bit7	Bit 6	Bit 5	Bit4	Bit3	Bit2	Bit1	Bit0
			V _{co}	м			
			VCOMR=0		VCOMR=1		
	000	000000	$V_{COM} = N.A.$		V _{COM} = N.A.		
	000	000001	$V_{COM} = N.A.$		V _{COM} = N.A.		
	000	000010	$V_{COM} = N.A.$		$V_{COM} = N.A.$		
			$V_{COM} = N.A.$		$V_{COM} = N.A.$		
	00	100111	$V_{COM} = N.A.$		V _{COM} = N.A.		
	00	101000	$V_{COM} = 0.80V$		V _{COM} = 0.20V		
	00	101001	$V_{COM} = 0.82V$		V _{COM} = 0.18V		
	00	101010	$V_{COM} = 0.84V$		V _{COM} = 0.16V		
	00	101011	V _{COM} = 0.86V		V _{COM} = 0.14V		
	00	101100	V _{COM} = 0.88V		V _{COM} = 0.12 V		
	11 ⁻	111101	V _{COM} = 5.06V		V _{COM} = -4.06 V		
	11	111110	V _{COM} = 5.08V		V _{COM} = -4.08 V		
	11	111111	V _{COM} = 5.10V		V _{COM} = -4.10 V		



OMT (0Ch)							
Bit7	Bit 6	Bit 5	Bit4	Bit3	Bit2	Bit1	Bit0
			V _{CON}	IT			
			VCOMR=0		VCOMR=1		
	000	00000	$V_{COMT} = N.A.$		$V_{COMT} = N.A.$		
	000	00001	$V_{COMT} = N.A.$		$V_{COMT} = N.A.$		
	000	00010	$V_{COMT} = N.A.$		$V_{COMT} = N.A.$		
			$V_{COMT} = N.A.$		V_{COMT} = N.A.		
	001	00111	$V_{COMT} = N.A.$		$V_{COMT} = N.A.$		P
	001	01000	$V_{COMT} = 0.80V$		V _{COMT} = 0.20V		
	001	01001	$V_{COMT} = 0.82V$		V _{COMT} = 0.18V		
	001	01010	$V_{COMT} = 0.84V$		V _{COMT} = 0.16V		
	001	01011	V _{COMT} = 0.86V		V _{COMT} = 0.14V		
	001	01100	V _{COMT} = 0.88V		V _{COMT} = 0.12 V	,	
					·····		
	111	11101	V _{COMT} = 5.06V		V _{COMT} = -4.06 V	/	
	111	11110	V _{COMT} = 5.08V		V _{COMT} = -4.08 V	/	
	111	11111	V _{COMT} = 5.10V		V _{COMT} = -4.10 V		

CONTROL (FFh)

	Bit7	Bit 6	Bit 5	Bit4	Bit3	Bit2	Bit1	Bit0	
	WED			Reserved				RED	
RED Bit The state of this bit determines whether read operations return the contents									

		of the DAC registers or the contents of the EEPROM
	[0]	0 Read operations return the contents of the DAC registers
		1 Read operations return the contents of the EEPROM
Reserved	Bit	These bits are reserved for future use. During write operations data
	[6:1]	intended for these bits is ignored, and during read operations 0 is returned
WED	Bit	Setting this bit forces the contents of all DAC registers to be copied into
		EEPROM, thereby making them the default values during power-up.
	[7]	When the contents of all the DAC registers have been written to the
		EEPROM, the P101automatically resets this bit.

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Version 0.03

Page 42 of 44



LAYOUT CONSIDERATION

System performance such as stability, transient response, and EMI is greatly affected by the PCB layout. Below are some general layout guidelines to follow when designing in the AAT1277.

Inductor

Always try to use shielded low EMI inductor with a ferrite core.

Bypass Capacitors

Place the low ESR ceramics bypass capacitors as close as possible to the VIN pin. This will help eliminate trace inductance effects and will minimize noise present on the internal supply rail. The ground connection of the VIN bypass capacitor should referenced to analog ground (AGND).

Output Capacitors

Minimize the trace length and maximize the trace width to minimize the parasitic inductance between the output capacitors of each regulator and its load for best transient response.

High Current Loop

The boost and buck regulators contain the high current loop. High current flows from the positive terminal of the input bulk capacitor, through the inductor, the catch diode, the output capacitor, to the negative terminal of the output capacitor, and back to the negative terminal of the input bulk capacitor. This high current path should be minimized in length and its trace width maximized. The inductor, catch diode, output capacitor should be placed as close as possible to the switch node LX (LX, VGH_LX, V25_LX). The input bulk capacitance should also be placed close to these power path components to shorten the power ground length between the input and output.

Feedback and Compensation Components

Any components for feedback should be placed as close as possible to its respective feedback pin. Minimize any feedback trace length to avoid noise pickup. Likewise, compensation components should be place as close as possible to the pin or device.

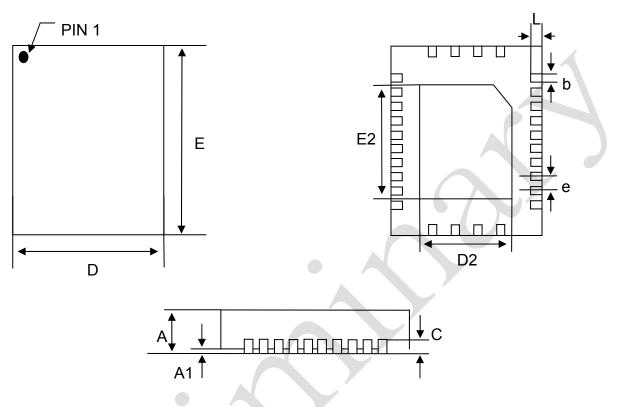
Ground Plane

Use a power ground plane for the boost and buck output capacitor ground, for the boost and buck input bulk capacitor ground, charge pump output capacitor grounds, and PGND pins (PGND1, PGND2). All power ground nodes should be connected using short trace length but wide trace width, which helps lower IR drops and minimize noise. Create an analog ground plane (AGND) for VIN bypass capacitor grounds, compensation component ground, feedback resistive network grounds, and also the AGND pins. Note that the IC's bottom side expose pad should also be connected to the analog ground plane. Analog ground (AGND) and power ground ((PGND1, PGND2) should be connected only at one signal point, near the expose pad by shorting the AGND pin to the expose pad.



PACKAGE DIMENSION

WQFN28-3.5X5.5



Symbol	Dimensions In Millimeters						
Symbol	MIN	TYP	MAX				
A	0.70	0.75	0.80				
A1	0.00	0.02	0.05				
b	0.20	0.25	0.30				
С		0.20					
D		3.50					
D2	1.95	2.05	2.10				
E		5.50					
E2	3.95	4.05	4.10				
е		0.50					
L	0.35	0.40	0.45				